



Automatic Application Of Neural Stimulation During Wheelchair Propulsion Enances Recovery Of Upright Sitting From Destabilizing Events

HYATT REGENCY DENVER & COLORADO CONVENTION CENTER · SEPTEMBER 3-6, 2017

- **Clinical Problem**

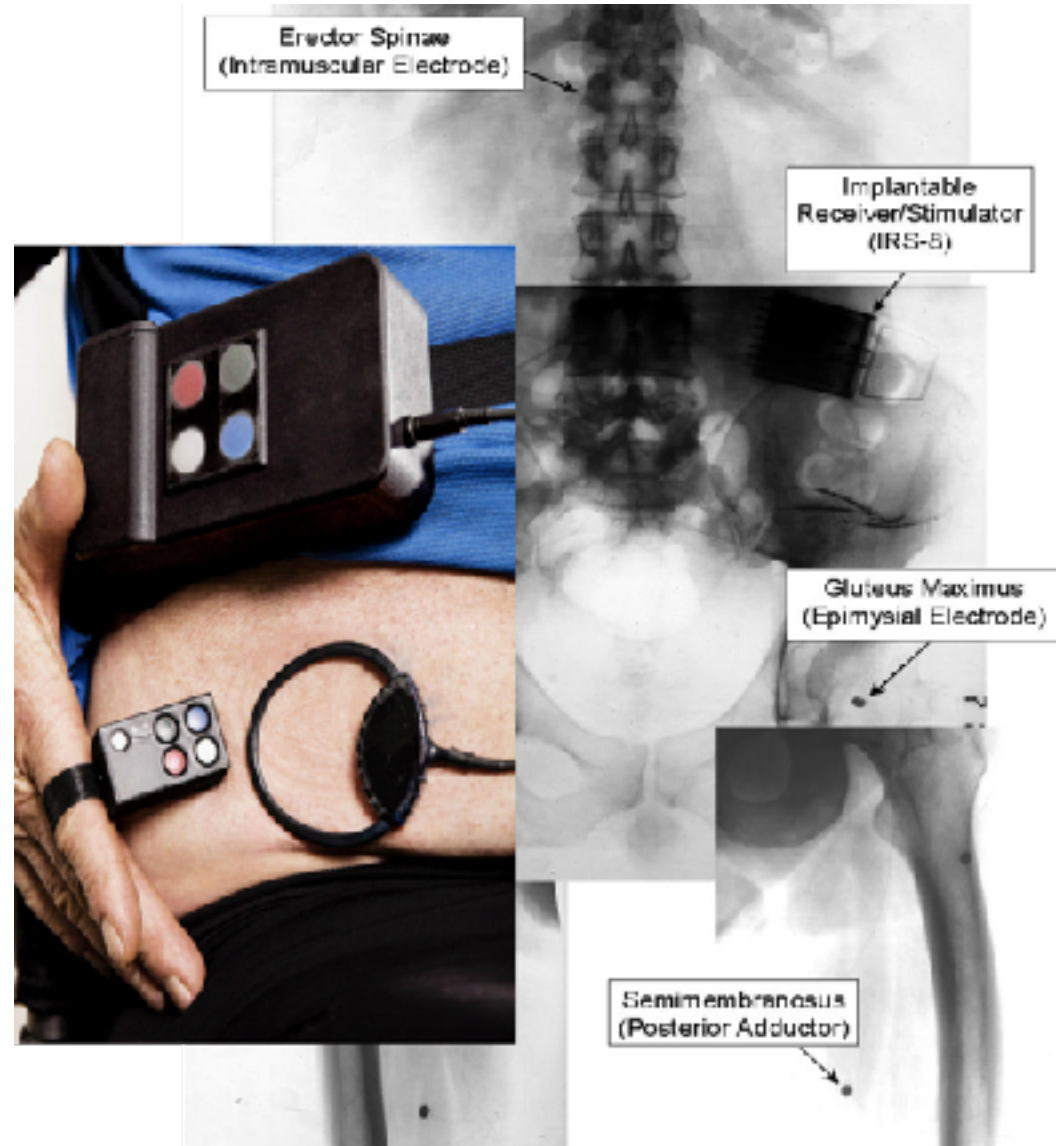
- Tips and falls are leading causes of injury for wheelchair users
- Riding surface and environmental factors contribute to wheelchair instability, and ultimately, falls
 - Collisions with obstacles, sharp turns, uneven or inclined surfaces, and curb drops

- **Conventional Approaches**

- Seat belts, cushions, and supports
 - Restrict desired motions in daily activities
 - Cause pressure ulcers, skin tears, lowered self-esteem, and even asphyxiation

Neural Stimulation

- Small currents applied to peripheral nerves cause otherwise paralyzed muscles to contract
- Intramuscular electrodes at T12-L-3 spinal nerves activate Erector Spinae (ES), Quadratus Lumborum (QL) & Iliopsoas (IL) to control lumbar spine & pelvis
- Electrodes inserted at gluteal & sciatic nerves extend & adduct the hip



Neural Stimulation can:

- Normalize vertebral alignment & restore anterior pelvic tilt
- Expand bimanual work volume & sagittal reach
- Stabilize sitting against perturbations by up to 45%
- Automatically return to erect for full forward flexion
- Enable retrieval of objects from the floor



WITHOUT Neural Stimulation



WITH Tilt-Triggered Stimulation

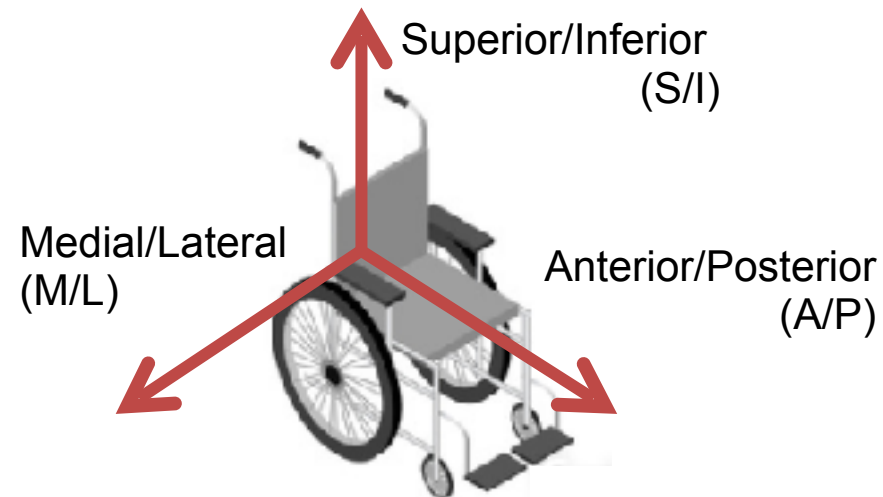
Kukke S, et al. IEEE TNSRE 12, 2004
Triolo R et al., APMR 90, 2009
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Audu ML et al., JNER 12(8), 2015.

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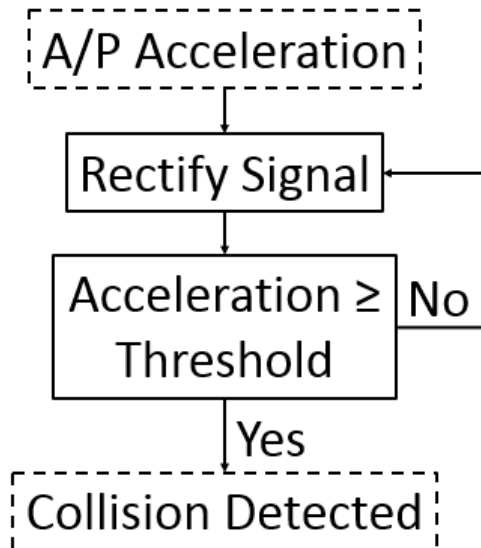
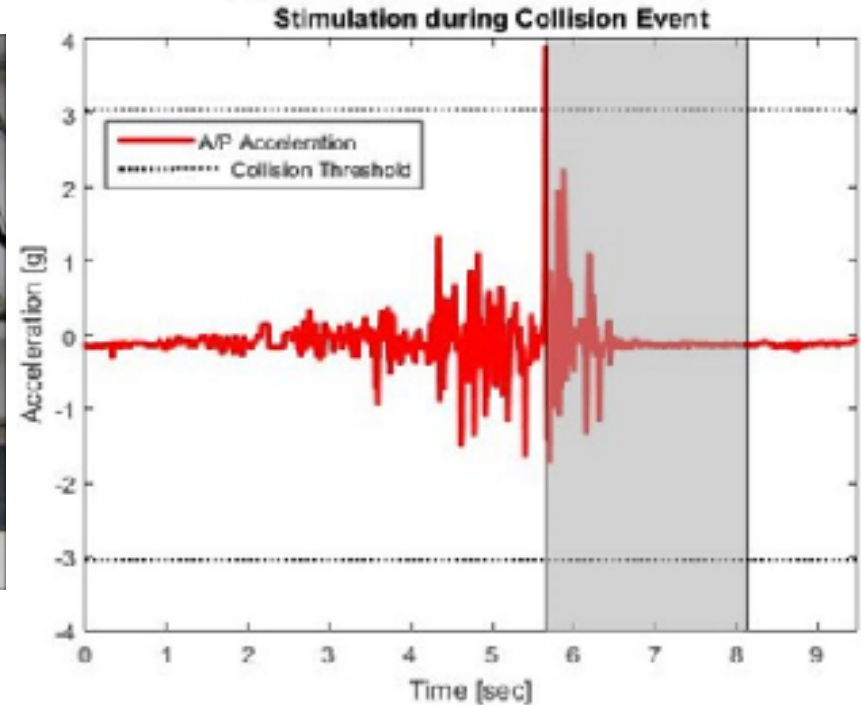
CONFIDENTIAL

1. Develop algorithms to automatically detect potentially destabilizing wheelchair conditions
 - Collisions
 - Sharp Turns
2. Generate appropriate stimulation patterns to activate hip and trunk muscles to regain or maintain stability
3. Evaluate system effectiveness in terms of objective and subjective measures

- Anthropomorphic Crash Dummy
 - Avoid potentially injurious experiments with live subjects
 - Collect preliminary data to standardize methods
- Wireless IMU (Inertial Measurement Unit)
 - Tri-axial accelerometers & gyroscopes
 - Affix to center rear crossbar
- VICON motion capture system



Collision Algorithm

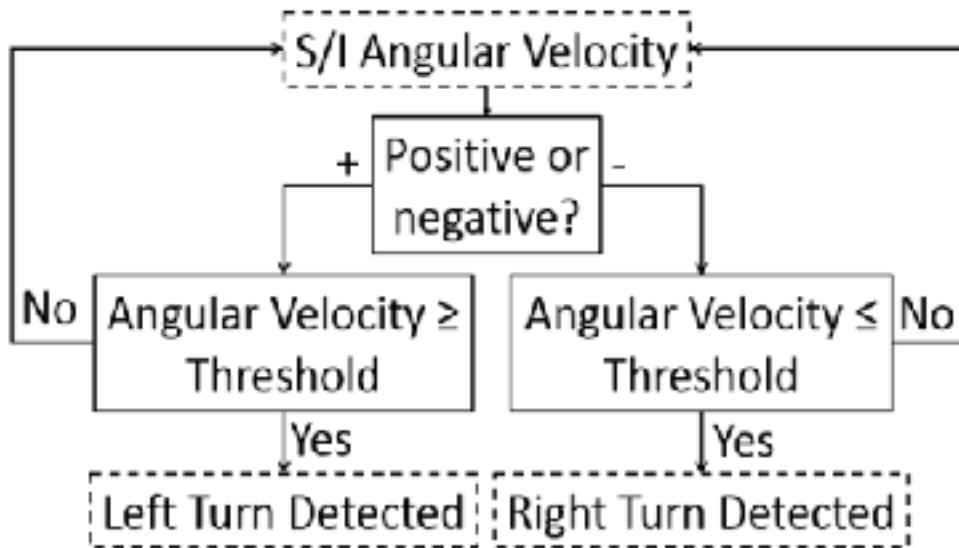
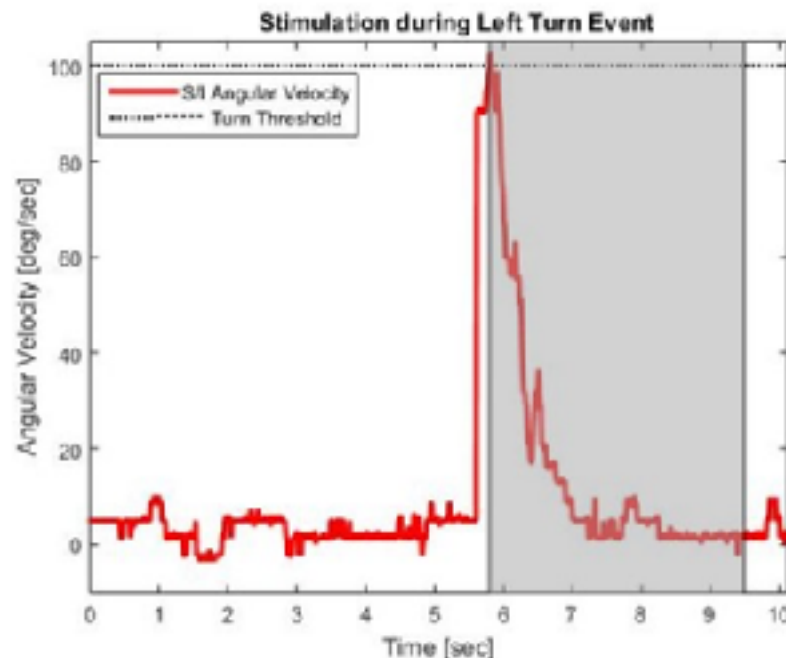


*Critical velocity = 1.75m/s

Consistent velocity ~ 1.5 m/sec
Peak deceleration ~ 4g

Threshold = Mean Peak $|AP_{acc}| - 2SD$

Turn Algorithm

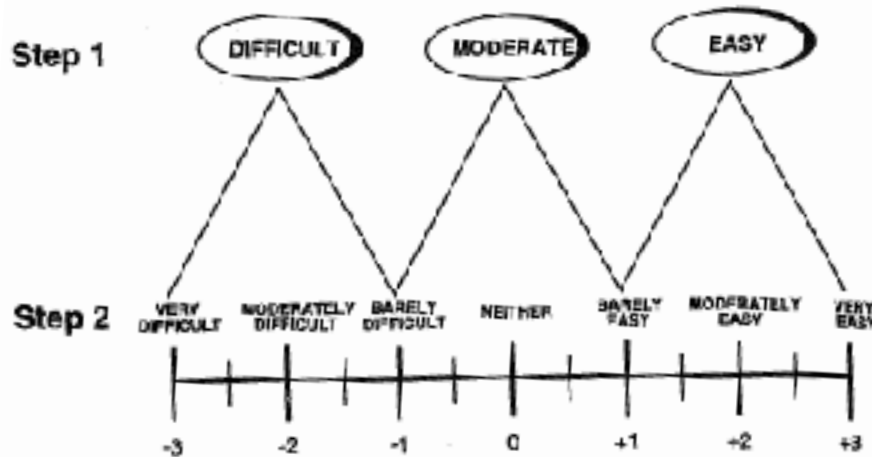


*Rollover risk > 1.5m/s @ 25cm radius

Turn threshold = Mean Peak $|SI_{av}| - 2SD$

Subject	Age	Gender	Injury Level	AIS Grade	Date of Injury
S1	51	M	C7	B	10/11/2002
S2	41	F	T3	A	2/13/2012
S3	59	M	T4	B	3/9/2008
S4	44	F	C7	C	3/13/1998

- Four implant recipients
- 20 Calibration Trials
 - WITHOUT stimulation
- 10 *Randomized* Test Trials
 - 5 WITH stimulation
 - 5 WITHOUT stimulation
- **Quantitative Outcomes**
 - Detection Accuracy
 - Detection Delay
 - Maximum Trunk Angle
 - Time to Restabilize Posture
- **Qualitative Outcomes**
 - Usability Rating Scale



Results: Collisions



WITHOUT
Stimulation

C7 AIS C

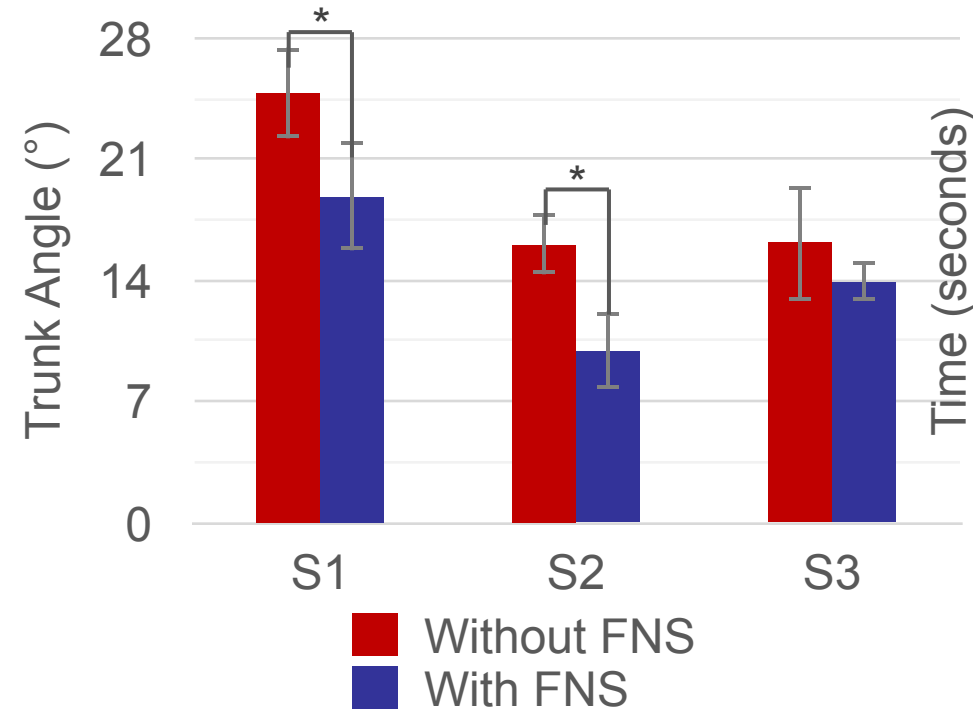


WITH
Stimulation

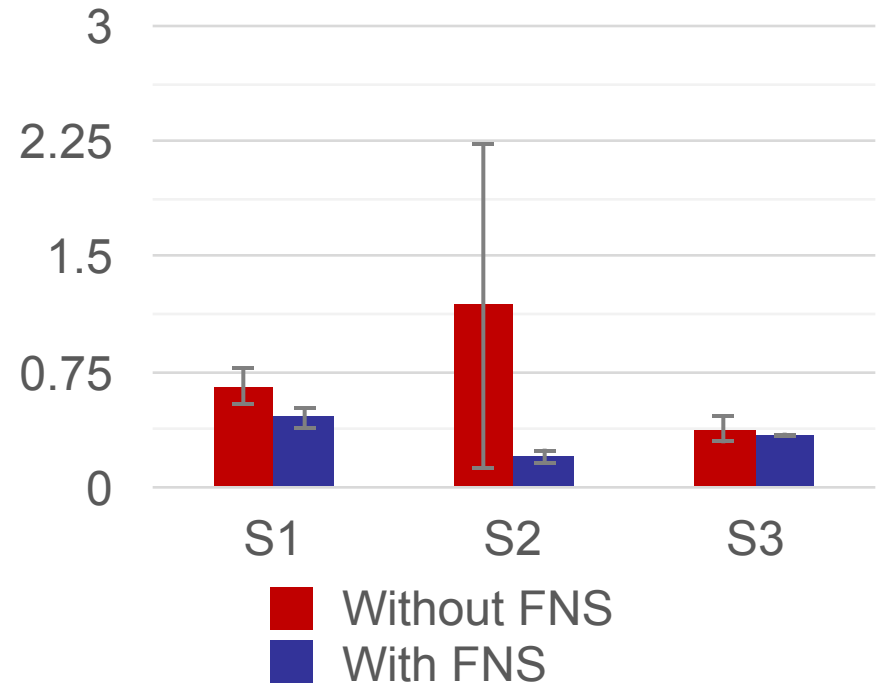
Results: Collisions

Detection Accuracy	Detection Delay
93%	63 ± 48 ms

Average Maximum AP Trunk Angle



Return Time to Erect Posture



Results: Collisions



WITHOUT
Stimulation

T4 AIS B

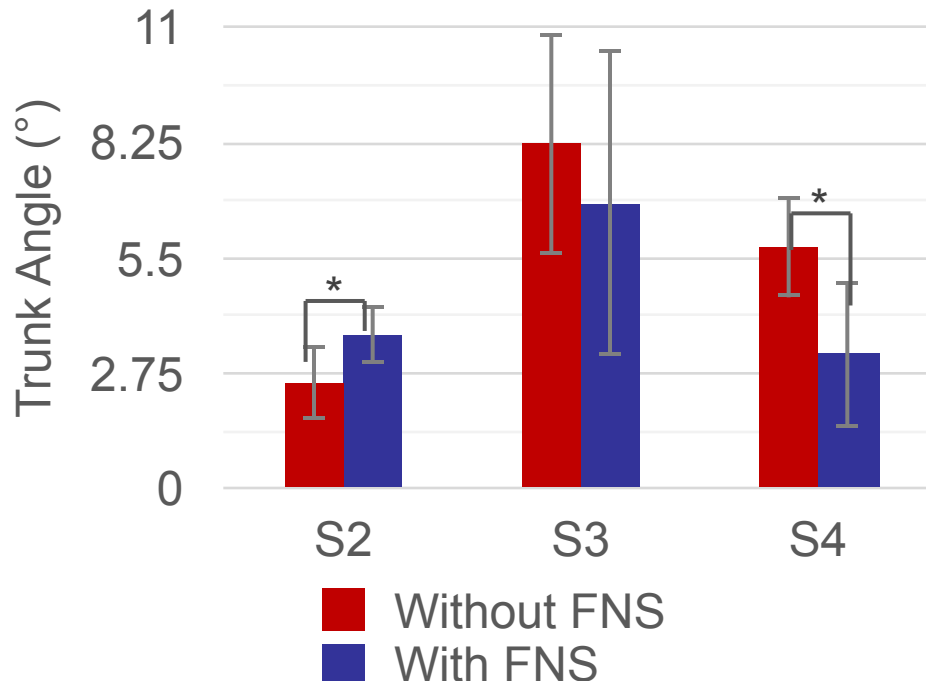


WITH
Stimulation

Results: Turns

Detection Accuracy	Detection Delay
90%	302 ± 90 ms

Average Maximum ML Trunk Angle



ML Lean Effects Mixed:

S2 increased

S3 unchanged

S4 reduced

Turn detection may be too slow to be effective

Preparatory strategies prior to turn

Results: URS

Median URS		S1	S2	S3	S4
Collisions	Without FNS	0	2	3	-
	With FNS	1	3	3	-
Turns	Without FNS	-	-3	2	-1
	With FNS	-	0	2	1

Subjective perceptions of ease/difficulty **improved** (S1, S2, S4) **or unchanged** (S3) with automatically triggered neural stimulation for BOTH collisions and turns, regardless of physical measurements

- Simple algorithms and inertial measurements accurately detect WC collisions (93%) and turns (90%)
- Appropriately timed hip & trunk muscle activation can improve recovery from forward collisions
 - Forward lean significantly reduced ($p < 0.05$) or unchanged
 - Return time varied but trended toward improvement
 - Collisions detected rapidly (63 ms) from WC acceleration
- Turns detected from WC angular velocity, while accurate, were too slow (309 ms) to be consistently effective
 - ML lean and recovery time results with stimulation mixed
 - Predictive inertial parameters (angular acceleration) need to be investigated
- Subjective ratings of difficulty improved with stimulation consistently (3/4 subjects) for both collisions & turns

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- S1, S2, S3, S4



T6 AIS A
(with stimulation)

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